### TOSHIBA MACHINE



#### Low cost Excellent performance at affordable prices.

#### Light weight

Up to 50% lighter than our previous models. Capable of reducing environmental impact.

Energy-efficient

Up to 50% reduction in required power-supply capacity compared with our previous models. Low-power consumption robots ideal for energy conservation era

#### Robot **Specifications**



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Model		THL700
Туре		Horizontal multi-joint
No. of controlled axes		4
Arm length		700mm (400mm+300mm)
Working	Axis 1	±125°
enve <b>l</b> ope	Axis 2	±145°
	Axis 3 (Z-axis)	0~150mm [Option:300mm]
	Axis 4 (Z-axis rotation)	±360°
Maximum *1	Axis 1	450°/s
speed	Axis 2	450°/s
	Axis 3 (Z-axis)	2000mm/s
	Axis 4 (Z-axis rotation)	1700°/s
	Composite	7 <b>.</b> 9m/s
Cycle time (with 2kg load) *2		0,50s
Maximum payload mass		10kg【Ratings:2kg】
Allowable moment of inertia		0.2kg·m <sup>2</sup>
Positioning*3	X—Y	±0.01mm
repeatabi <b>l</b> ity	Z (Axis 3)	±0.015mm
	Axis θ (Z-axis rotation)	±0.007°
Hand wiring		8 inputs/8 outputs
Hand pneumatic joints *4		φ6 ×3 pcs
Position detection		Absolute
Robot controller cable		3"5m
Mass		24kg
*1 . A analoration	decoloration rates may be li	mitad according to the motion pattern

- \*1 : Acceleration/deceleration rates may be limited according to the motion pattern, load mass and amount of offset.

  \*2 : When the environment temperature is constant 20°C. Positioning repeatable accuracy in one-direction movement. Not absolute positioning accuracy.

  \*3 : Horizontal 300mm, vertical 25mm, round-trip. Continous operation is not possible beyond the effective load ratio.

- \*4 : Pneumatic joints are provided on the base. Please refer to the drawings for the details of the pneumatic joints. Pipes to be are provided by the customers.

#### Controller **Specifications**

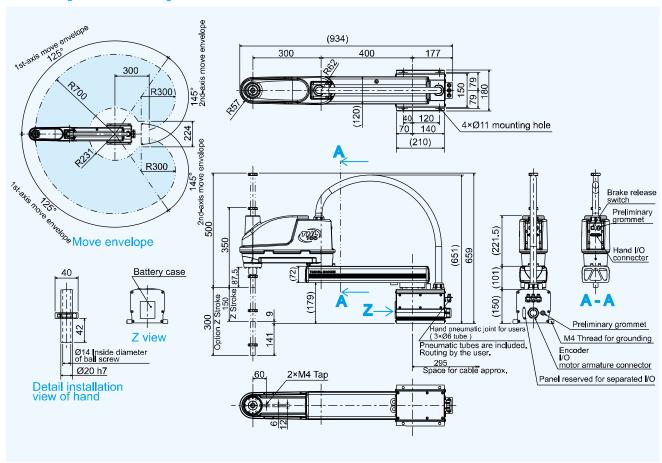


**TEACH PENDANT(OPTION)** 

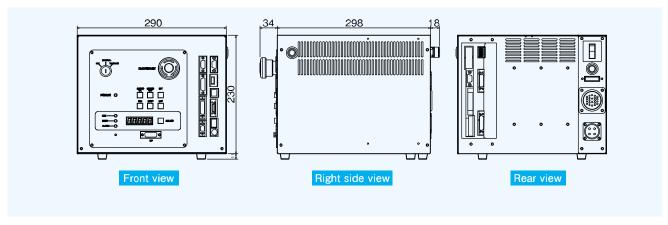
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Model	TS3000		
Number of axis	Standard 4 axis (Maximum 5 axis)		
Operation mode	PTP, CP (linear, Circular), Short-cut, Arch motion		
Storage capacity	Approx. Total:12800points+25600steps		
	1 program:2000points+3000steps		
Number of programs	Maximum 256 (247 user files+9 system files)		
Programming language	SCOL (similar to BASIC)		
Teaching unit	Teach pendant TP1000:Cable length 5m		
	(Programming support PC software TSPC also available)		
External I/O signals	32 inputs/32 outputs		
Hand control signals	8/8 can be assigned to system signals.		
External operation	Input:cycle operation mode, start, stop, program reset, etc		
signal	Output:Servo ON, operation ready, fault, etc		
Serial communication port	RS232C:2ports (HOST, COM1), Ethernet 1port *5		
Other functions	Torque control, interrupt function, self diagnosis,		
	I∕O control, communication during motion,		
	coordinate calculations, built-in PLC,		
	conveyor synchronisation etc.		
Power supply	Single phase, AC200V~240V 50 / 60Hz		
Power capacity	1.4kVA		
Outer Dimensions and Mass	290 (W)×230 (H)×298 (D) [mm],13kg		
PC Software for Programming	TSPC:Program editor, teaching, remote operation		
Support (Option)	TCPRGOS:PLC sequence program creation		
Options	I/Oextension, I/Ocables,		
	Field-Network (CC-Link, DeviceNet, Profibus)*5		
External memory	USB memory stick		

\*5:Ethernet is a registered trademark of XEROX Corp. in the U.S.A. CC-Link is a registered trademark of CC-Link Partner Association. DeviceNet is a registered trademark of ODVA. Profibus is a registered trademark of Profibus User Organization.

#### THL700[External View]



#### TS3000[External View]



# **TOSHIBA MACHINE CO.,LTD.** HEAD OFFICE Control Systems Sales Department, Control Systems Division 2068-3, Ooka, Numazu-shi, Shizuoka-ken 410-8510, Japan TEL:[81]-(0)55-926-5032 FAX:[81]-(0)55-925-6527

## **TOSHIBA MACHINE CO., AMERICA.** 755 Greenleaf Avenue, ElK Grove Village, IL 60007, U.S.A. TEL:[1]-847-593-1616 FAX:[1]-847-593-0897

#### TM ROBOTICS (EUROPE) LTD.

Unit 2, Bridge Gate Centre, Martinfield, Welwyn Garden City, Herts AL7 1JG, UK TEL [44]-(0)1707-290370 FAX [44]-(0)1707-376662

URL:http://www.toshiba-machine.co.jp/en/product/robot/index.html http://www.toshiba-machine.com http://www.tmrobotics.co.uk



Before operating the industrial robot, read through and completely understand the instruction manuals.

■The contents included in this catalog are subject to change without prior notice to reflect improvements.